

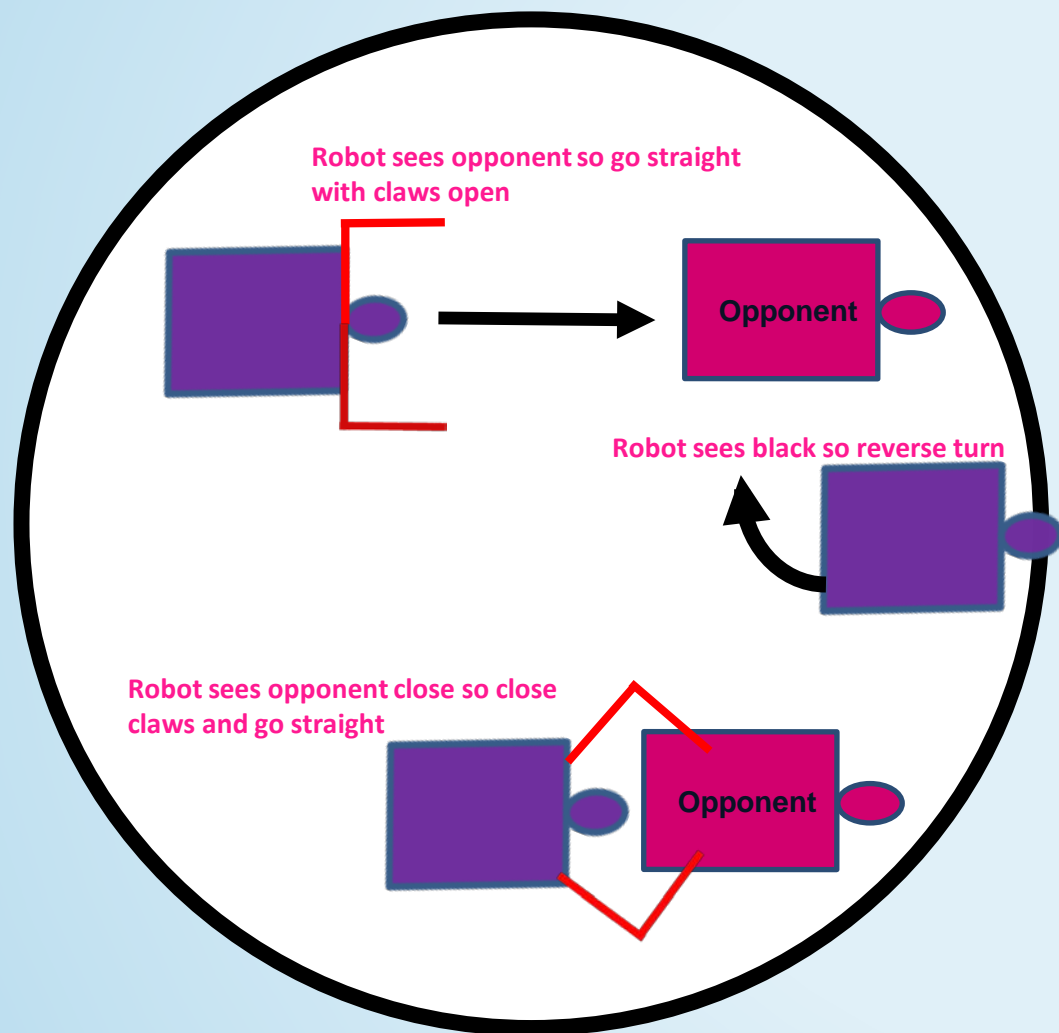
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SUMO Algorithm

Stay in Ring + Scan and Charge + CLAWS
1 Colour / Light Sensor, 1 Ultrasonic



SUMO Algorithm: Stay in Ring + Scan and Charge + CLAWS



IF robot sees black

THEN reverse

ELSE check ultrasonic

IF opponent far

THEN charge with claws open

IF opponent close

THEN charge claws closed

ELSE Scan (turn)

Sumo Algorithm

One Colour /Light Sensor and Ultrasonic

